

Theorems in Linear Algebra, Lay, 3rd ed.

Solutions of Linear Systems: A system of linear equations has either

1. no solution, or
2. exactly one solution, or
3. infinitely many solutions.

Augmented Matrices: If the augmented matrices of two linear systems are *row equivalent*, then the two systems have the same solution set, i.e., they are *equivalent*.

Theorem 1 (Chap. 1): Uniqueness of the Reduced Echelon Form: Each matrix is row equivalent to one and only one reduced echelon matrix.

Theorem 2 (Chap. 1): Existence and Uniqueness of Solutions to a SOLE:

- A SOLE is consistent if and only if the rightmost column of its augmented matrix is *not* a pivot column.
- A consistent SOLE has a *unique* solution iff there are no free variables.
- A consistent SOLE has *infinitely many* solutions iff there is at least one free variable.

Algebraic Properties of R^n : For all $\mathbf{u}, \mathbf{v}, \mathbf{w}$ in R^n and all scalars c and d :

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|--|---------------|--|----------------|
| (i) $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$ | (commutative) | (v) $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$ | (distributive) |
| (ii) $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$ | (associative) | (vi) $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$ | (distributive) |
| (iii) $\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$ | (identity) | (vii) $c(d\mathbf{u}) = (cd)(\mathbf{u})$ | (associative) |
| (iv) $\mathbf{u} + (-\mathbf{u}) = -\mathbf{u} + \mathbf{u} = \mathbf{0}$, | (inverse) | (viii) $1\mathbf{u} = \mathbf{u}$ | (identity) |
- where $-\mathbf{u}$ denotes $(-1)\mathbf{u}$

Theorem 3 (Chap. 1): If A is an $m \times n$ matrix, with columns $\mathbf{a}_1, \dots, \mathbf{a}_n$ (in R^m), and if \mathbf{b} is in R^m , the matrix equation

$$A\mathbf{x} = \mathbf{b}$$

has the same solution set as the vector equation

$$x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n = \mathbf{b}$$

which, in turn, has the same solution set as the SOLE whose augmented matrix is

$$[\mathbf{a}_1 \ \mathbf{a}_2 \ \dots \ \mathbf{a}_n \ \mathbf{b}]$$

Existence of Solutions: The equation $A\mathbf{x} = \mathbf{b}$ has a solution iff \mathbf{b} is a linear combination of the columns of A .

Theorem 4 (Chap. 1): Let A be an $m \times n$ matrix. Then the following statements are logically equivalent. That is, for a particular A , either they are all true statements or they are all false.

- For each \mathbf{b} in R^m , the equation $A\mathbf{x} = \mathbf{b}$ has a solution.
- Each \mathbf{b} in R^m is a linear combination of the columns of A .
- The columns of A span R^m .
- A has a pivot position in every row.

Theorem 5 (Chap. 1): Linearity of Matrix-Vector Product: If A is an $m \times n$ matrix, \mathbf{u} and \mathbf{v} are vectors in R^n , and c is a scalar, then:

- $A(\mathbf{u} + \mathbf{v}) = A\mathbf{u} + A\mathbf{v}$;
- $A(c\mathbf{u}) = c(A\mathbf{u})$.

Homogeneous Equation - Nontrivial Solution: The homogeneous equation $A\mathbf{x} = \mathbf{0}$ has a nontrivial solution iff the equation has at least one free variable.

Theorem 6 (Chap. 1): Suppose the equation $A\mathbf{x} = \mathbf{b}$ is consistent for some given \mathbf{b} , and let \mathbf{p} be a solution. Then the solution set of $A\mathbf{x} = \mathbf{b}$ is the set of all vectors of the form $\mathbf{w} = \mathbf{p} + \mathbf{v}_h$, where \mathbf{v}_h is any solution of the homogeneous equation $A\mathbf{x} = \mathbf{0}$.

Linearly Independent Columns: The columns of a matrix A are linearly independent iff the equation $A\mathbf{x} = \mathbf{0}$ has *only* the trivial solution.

Linear Independence for One Vector: A set containing only one vector \mathbf{v} is linearly independent iff $\mathbf{v} \neq \mathbf{0}$.

Linear Independence for Two Vectors: A set of two vectors $\{\mathbf{v}_1, \mathbf{v}_2\}$ is linearly dependent iff at least one of the vectors is a multiple of the other. The set is linearly independent iff neither of the vectors is a multiple of the other.

Theorem 7 (Chap. 1): Characterization of Linearly Dependent Sets: An indexed set $S = \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ of two or more vectors is linearly dependent iff at least one of the vectors in S is a linear combination of the others. In fact, if S is linearly dependent and $\mathbf{v}_1 \neq \mathbf{0}$, then some \mathbf{v}_j (with $j > 1$) is a linear combination of the preceding vectors, $\mathbf{v}_1, \dots, \mathbf{v}_{j-1}$.

Theorem 8 (Chap. 1): More Vectors than Entries: If a set contains more vectors than there are entries in each vector, then the set is linearly dependent. That is, any set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in R^n is linearly dependent if $p > n$.

Theorem 9 (Chap. 1): Set Containing the Zero Vector: If a set $S = \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in R^n contains the zero vector, then the set is linearly dependent.

Properties of Linear Transformations: If T is a linear transformation, then

- (i) $T(\mathbf{0}) = \mathbf{0}$, and
- (ii) $T(c\mathbf{u} + d\mathbf{v}) = cT(\mathbf{u}) + dT(\mathbf{v})$ for all vectors \mathbf{u}, \mathbf{v} in the domain of T and all scalars c, d . More generally
 $T(c_1\mathbf{v}_1 + \dots + c_p\mathbf{v}_p) = c_1T(\mathbf{v}_1) + \dots + c_pT(\mathbf{v}_p)$.

Theorem 10 (Chap. 1.): Matrix of a Linear Transformation: Let $T : R^n \rightarrow R^m$ be a linear transformation. Then there exists a unique matrix A such that

$$T(\mathbf{x}) = A\mathbf{x} \quad \text{for all } \mathbf{x} \text{ in } R^n$$

In fact, A is the $m \times n$ matrix whose j th column is the vector $T(\mathbf{e}_j)$, where \mathbf{e}_j is the j th column of the identity matrix in R^n :

$$A = [T(\mathbf{e}_1) \quad \dots \quad T(\mathbf{e}_n)]$$

The matrix A is called the **standard matrix for T** .

Theorem 11 (Chap. 1): One-to-One: Let $T : R^n \rightarrow R^m$ be a linear transformation. Then T is one-to-one iff the equation $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Theorem 12 (Chap. 1): One-to-One, Onto, Standard Matrix: Let $T : R^n \rightarrow R^m$ be a linear transformation and let A be the standard matrix for T . Then:

- a. T maps R^n onto R^m iff the columns of A span R^m ;
- b. T is one-to-one iff the columns of A are linearly independent.